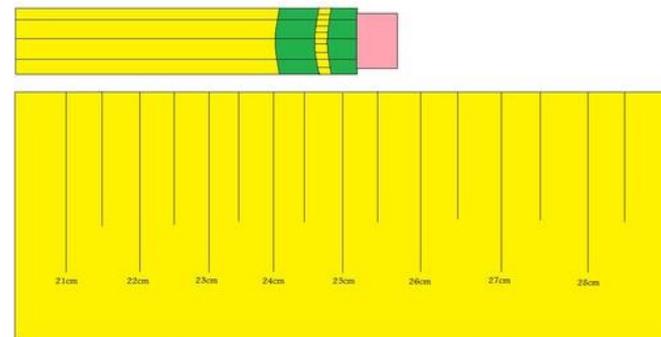


Good accuracy
Good precision

Poor accuracy
Good precision

Poor accuracy
Poor precision



Error Analysis

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PHYS 3110

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http://wps.prenhall.com/wps/media/objects/165/169061/SW-comart/fig1_2_5.gif
http://chemwiki.ucdavis.edu/@api/deki/files/430/Measuring_pencil.jpg?size=bestfit&width=423&height=241&revision=1



UNIVERSITY OF HOUSTON
Learning. Leading.

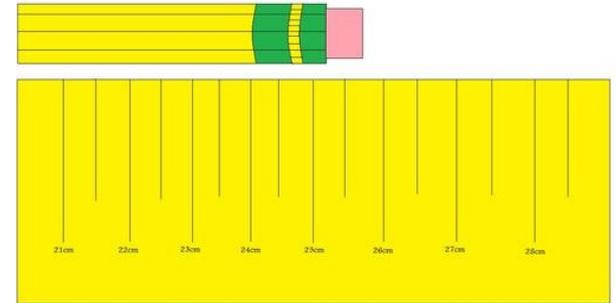
Types of Error

- Instrumental
- Observational
- Environmental
- Theoretical



Types of Error

- Instrumental
 - Accuracy limits of instrument
 - Poorly calibrated instrument
 - Fluctuating signal
 - Broken instrument
- Observational
- Environmental
- Theoretical



Types of Error

- Instrumental
- Observational
 - Parallax
 - Misused instrument
- Environmental
- Theoretical



Types of Error

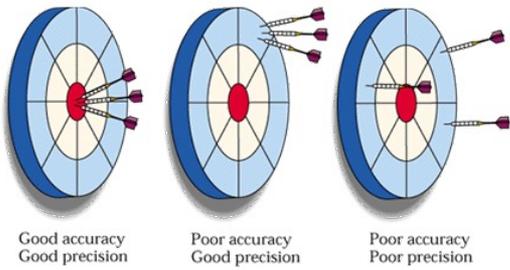
- Instrumental
- Observational
- Environmental
 - Electrical power brown-out, causing low current
 - Local magnetic field not accounted for
 - wind
- Theoretical



Types of Error

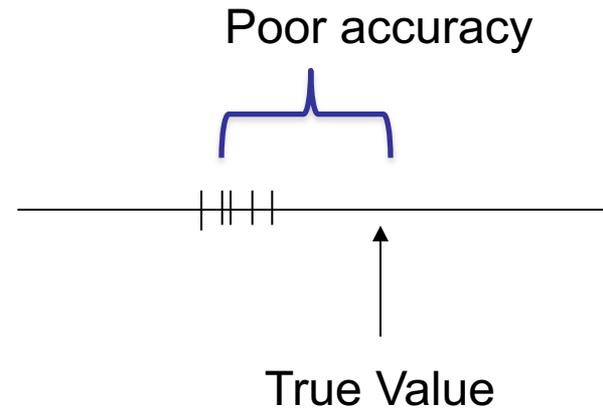
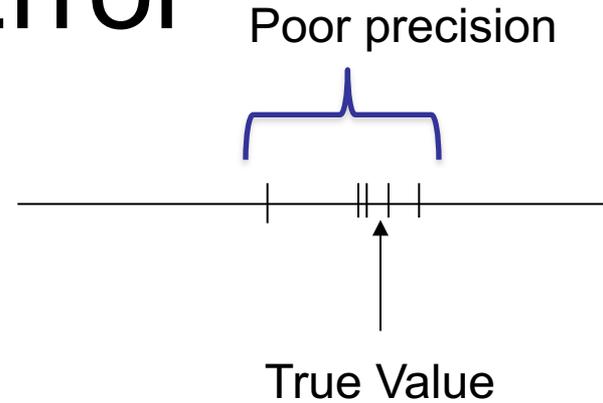
- Instrumental
- Observational
- Environmental
- Theoretical
 - Effects not accounted for or incorrectly ignored
 - Friction
 - Error in equations





Types of Error

- Random
 - Can be quantified by statistical analysis
- Systematic
 - Try to identify and get rid of
 - Hopefully found during analysis; may need to repeat experiment!



Error for Different Types of Quantities

- Measured Quantities
 - N Independent measurements of the same physical quantity
 - Measurement of a series of N quantities that are dependent on an independent value, i.e. $x(t)$ or $I(V)$.
- Calculated quantities
 - Propagation of error



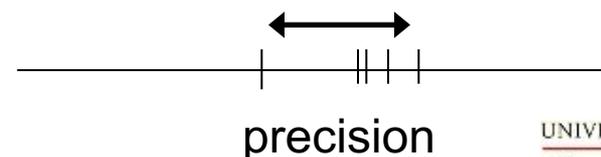
Statistical Analysis of Random Error

- For n independent measurements, they should group around the true value. For large n , the average should tend to the true value
- If the measurements are independent, can find the standard deviation, σ . σ proportional to width of the distribution.

$$\bar{x} \rightarrow x$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

$$\sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2}$$



Standard deviation of the mean

- $\sigma_m = \sigma/n^{1/2}$

$$\sigma_m = \sqrt{\frac{1}{n(n-1)} \sum_{i=1}^n (x_i - \bar{x})^2}$$

- For $n > 1$ measured values, report : $x = \bar{x} \pm \sigma_m$

- If $\sigma_m = 0$ or $<$ roughly 1/10 precision, use accuracy of measurement device for reported error.

- If there is no systematic error, there is a $\sim 2/3$ probability that the true value is within $\pm \sigma_m$



Reporting Error

$$\bar{X} \pm \sigma_m$$

- Significant figures:
 - σ_m : one (sometimes two) sig. figs.
 - X_{ave} : same precision as σ_m

$$G = 6.674\ 30 \times 10^{-11} \\ \pm 0.000\ 15 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}$$

NIST, Fundamental Constants, https://physics.nist.gov/cgi-bin/cuu/Value?bg|search_for=universal_in!
accessed 8/29/23.

$$\text{Length} = 1.53 \pm 0.05 \text{ m}$$



σ and σ_m

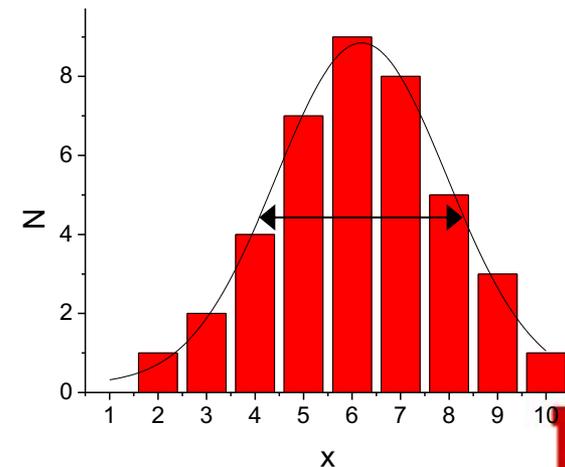
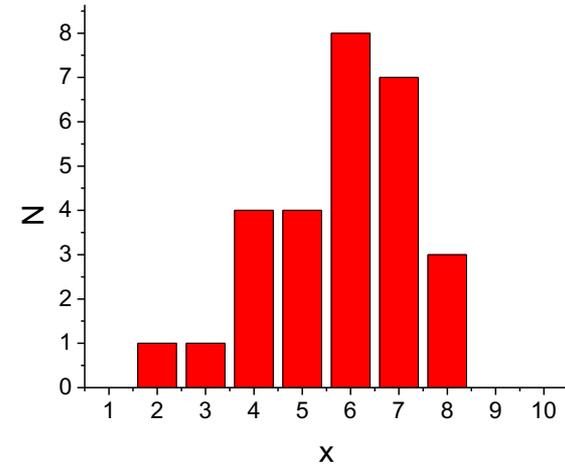
- σ represents the error in one measurement
- σ_m represents the error in the mean of n measurements



Gaussian Distribution

- Plot of measured value, versus number (N) of times that value was measured.
- If error is random, for large n, this distribution tends to a Gaussian distribution.

$$N(x) = \frac{n}{\sqrt{2\pi} \sigma} e^{-\frac{(x-\bar{x})^2}{2\sigma^2}}$$



$$\text{Fwhm} \cong 2.4\sigma$$



Gaussian Distribution

- Probability of one measurement being x ,

$$P(x) = N(x)/n \quad P(x) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{(x-\bar{x})^2}{2\sigma^2}}$$

- The probability of a measurement being within

$\pm\sigma$ of x_{ave} :

$$P(\text{within } \sigma) = \int_{\bar{x}-\sigma}^{\bar{x}+\sigma} P(x) dx$$

- Probability of being within $n\sigma$:

$$\pm 1\sigma = 68.3\%$$

$$\pm 2\sigma = 95.5\%$$

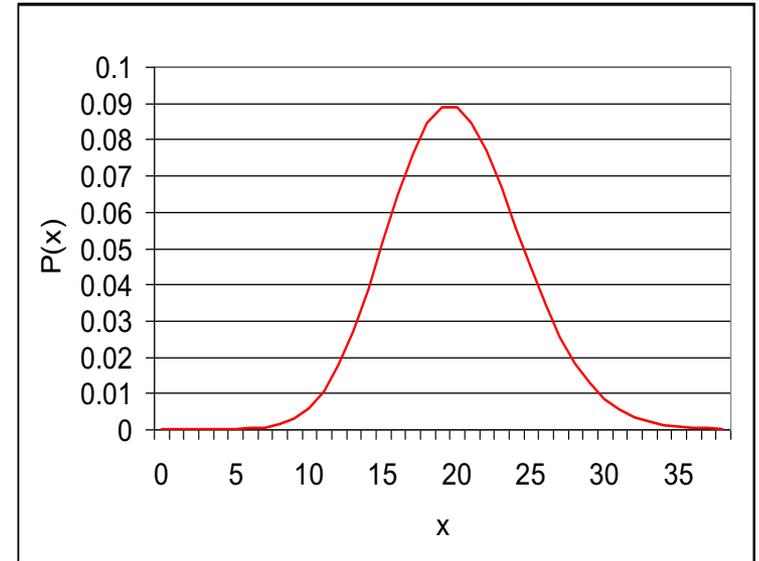
$$\pm 3\sigma = 99.7\%$$



Poisson Distribution

$$P(x) = \frac{(\bar{x})^x e^{-\bar{x}}}{x!}$$

- Applies to processes described by an exponential, such as radioactive decay
- standard deviation $\sigma = \sqrt{x}$
- For large x_{ave} , i.e. for long counting times, the Poisson distribution tends to a Gaussian distribution with the same ave. and σ .



Reporting Error from a Poisson Process

- When measuring a physical process that you expect to follow a Poisson distribution, the error in one measurement is

$$x = x \pm \sigma = x \pm \sqrt{x}.$$

- Example:
 - Measuring the intensity of radiation emitted by an α source and scattered by gold nuclei, at an angle θ , over 30 seconds.



Propagation of Errors

- Determining the error in a quantity calculated from measured data.
- Let x , y , z be measured values
- Let δx , δy , δz be the corresponding estimated errors in the measurements.
 $x \pm \delta x$, etc.
- If one measurement, $\delta x =$ accuracy of the instrument. If n measurements of x , then use $x \pm \sigma_x$, where σ_x is the standard deviation of the mean of x .



Propagation of Errors

- Let $w(x,y,z)$ be a function of measured values. We want to find δw , the error in w .
- If the errors are uncorrelated, we assume $dx \approx \delta x$,
- If the errors are correlated, there are cross terms like

differential :

$$dw = \frac{\partial w}{\partial x} dx + \frac{\partial w}{\partial y} dy + \frac{\partial w}{\partial z} dz$$

$$\delta w = \sqrt{\left(\frac{\partial w}{\partial x} \delta x\right)^2 + \left(\frac{\partial w}{\partial y} \delta y\right)^2 + \left(\frac{\partial w}{\partial z} \delta z\right)^2}$$

$$\delta w^2 = \sum_i \left(\frac{\partial w}{\partial x_i} \delta x_i\right)^2$$

$$\frac{\partial w}{\partial x} \frac{\partial w}{\partial y} \text{cov}(\delta x, \delta y)$$



Propagation of Errors

$$\delta w^2 = \sum_i \left(\frac{\partial w}{\partial x_i} \delta x_i \right)^2$$

Some Examples:

- $w = ax + by + cz$ $\delta w = \sqrt{(a\delta x)^2 + (b\delta y)^2 + (c\delta z)^2}$

- $w = k x^a y^b z^c$ $\delta w = \sqrt{\left(\frac{aw\delta x}{x}\right)^2 + \left(\frac{bw\delta y}{y}\right)^2 + \left(\frac{cw\delta z}{z}\right)^2}$

$$\partial w / \partial x = a k x^{a-1} y^b z^c$$

$$\partial w / \partial x = aw/x$$

$$\frac{\delta w}{w} = \sqrt{\left(\frac{a\delta x}{x}\right)^2 + \left(\frac{b\delta y}{y}\right)^2 + \left(\frac{c\delta z}{z}\right)^2}$$

- During lab, for a quick error estimate, just use the biggest term.



% Error

- Precision = % error = $(\delta x/x) * 100\%$
- Accuracy = % error compared to accepted
= $|x_{\text{calculated}} - x_{\text{accepted}}|/x_{\text{accepted}} * 100\%$
- % difference = $|x_1 - x_2|/(|x_1 + x_2| / 2) * 100\%$

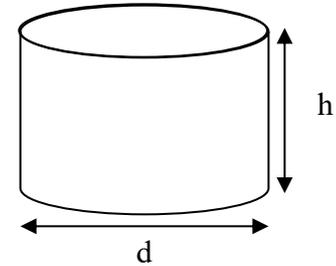


Example: Density of a Cylinder

$$\rho = m/V$$

$$\rho = m/(\pi r^2 h)$$

$$\rho = \frac{\bar{m}}{\frac{\pi}{4} \bar{d}^2 \bar{h}}$$



$$\delta\rho = \sqrt{\left(\frac{\partial\rho}{\partial m} \delta m\right)^2 + \left(\frac{\partial\rho}{\partial d} \delta d\right)^2 + \left(\frac{\partial\rho}{\partial h} \delta h\right)^2}$$

$$\delta\rho = \sqrt{\left(\frac{\rho}{m} \delta m\right)^2 + \left(\frac{2\rho}{d} \delta d\right)^2 + \left(\frac{\rho}{h} \delta h\right)^2}$$

Check your
units!



Density of a Cylinder

$$\rho = \frac{m}{\frac{\pi}{4} d^2 h} \quad \delta\rho = \sqrt{\left(\frac{\rho}{m} \delta m\right)^2 + \left(\frac{2\rho}{d} \delta d\right)^2 + \left(\frac{\rho}{h} \delta h\right)^2}$$

Assume, after measuring d, h, and m three times each, you get

$$m = 492.0 \pm 0.5 \text{ g}$$

$$h = 11.00 \pm 0.01 \text{ cm}$$

$$d = 4.00 \pm 0.02 \text{ cm}, \quad \rho = 3.559 \text{ g/cm}^3$$

But precession of tools are 0.5 g and 0.15 cm.

$$\delta\rho = 3.559 \frac{\text{g}}{\text{cm}^3} \sqrt{\left(\frac{0.5 \text{ g}}{492.0 \text{ g}}\right)^2 + \left(\frac{2 \times 0.02 \text{ cm}}{4.00 \text{ cm}}\right)^2 + \left(\frac{0.15 \text{ cm}}{11.00 \text{ cm}}\right)^2}$$

$$\delta\rho = 3.559 \frac{\text{g}}{\text{cm}^3} \sqrt{0.001^2 + 0.010^2 + 0.014^2} = 0.0613 \frac{\text{g}}{\text{cm}^3}$$

Sig. Figs.

$$\rho = 3.56 \pm 0.06 \text{ g/cm}^3, \quad \delta\rho/\rho = 0.02, \quad 2\% \text{ error}$$



Density of a Cylinder

$$\rho = \frac{m}{\frac{\pi}{4} d^2 h} \quad \delta\rho = \sqrt{\left(\frac{\rho}{m} \delta m\right)^2 + \left(\frac{2\rho}{d} \delta d\right)^2 + \left(\frac{\rho}{h} \delta h\right)^2}$$

$$\delta\rho = 3.559 \frac{g}{cm^3} \sqrt{\left(\frac{0.5 g}{492.0 g}\right)^2 + \left(\frac{2 \times 0.02 cm}{4.00 cm}\right)^2 + \left(\frac{0.15 cm}{11.00 cm}\right)^2}$$

$$\delta\rho = 3.559 \frac{g}{cm^3} \sqrt{0.001^2 + 0.010^2 + 0.014^2} = 0.0613 \frac{g}{cm^3}$$

Which term contributes most to error?

How can you reduce the error?

Rule of thumb: If more than 10 measurements of a single variable are needed, use a better instrument or method to reduce σ_m .



Weighted Average

- n values, each with their own error, $x_i \pm \sigma_i$
- The error in this weighted mean can be found from propagation of error

$$\bar{x} = \frac{\sum_{i=1}^n x_i \left(\frac{1}{\sigma_i}\right)^2}{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2}$$

$$\delta\bar{x} = \frac{\sqrt{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^4 \sigma_i^2}}{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2}$$

$$\frac{\partial \bar{x}}{\partial x_i} = \frac{\left(\frac{1}{\sigma_i}\right)^2}{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2}$$

$$\delta\bar{x} = \frac{\sqrt{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2}}{\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2} = \left(\sum_{i=1}^n \left(\frac{1}{\sigma_i}\right)^2 \right)^{-1/2}$$



Weighted Mean Examples

- You measure 5 sets of (E, T) data to try to find σ in the Stephan-Boltzmann Law, $E = \sigma T^4$
- You can't average E & T and find one σ from the average.
- Find 5 σ 's, find the weighted mean using the 5 $\delta\sigma$'s calculated from propagation of error, then find the uncertainty of the weighted mean.



Homework

- Find the density of your Cougar One Card (UH ID card) and find the estimated error in the density.
 - Find the standard deviation of the mean for each measured value. Compare it to the uncertainty in the measurements and decide which to use. Explain your choices.
 - Use propagation of error to find the uncertainty in the density. Show the equation you derive.
 - Your precision should be less than 30%.

